## **Overall Risk Management**

 isk ID	Risk Name	Mitigation Strategy
1	Noisy detection in moving data	Make height adjustment design robust with Base Support. <u>(Solved with new pan tilt design</u> and new HD camera)
2	Intraface crashes	Get a more stable version of Intraface for the system. <u>(solved using ros::spawn())</u>
3	•	Request sponsors & new set of batteries ( <u>5</u> spare batteries collected)
4	Single robot failure	<ul> <li>a. Make the swarm robust to work without the non-operative robot. <u>(ROCON)</u></li> <li>b. Ask sponsor &amp; get custody of 2 extra turtlebot. <u>(5 turtlebots spare in lab)</u></li> </ul>
5	Multiple faces in vicinity	Use zoom features and crop the image frame. Then input to Intraface

