# Autonomous Aerial Assistance for Search and Rescue

**Progress Review 11** April 5th, 2017

**Team F** 

# Tasks

- Investigate and Resolve issues with bounding boxes on RGB/Thermal
- Investigate and Resolve GPS location estimation issues
- Integrate GPS estimation with Signature detection
- Processing Pipeline
- Code migration to Python

## Thermal and RGB algorithm integration

- Modification
  - Add drifts for mapping the ROIs in Thermal and RGB images
  - Integrate the ROIs from both the algorithms
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- Pixel position of both human and bright signature
- Timestamps which are in accordance with the position info
- Images with human bounding boxes
- Save the RGB and Thermal data in two separate folders

RGB/00145.bmp 11:24:02.133 1524 63 B RGB/00146.bmp 11:24:02.167 1545 84 B RGB/00147.bmp 11:24:02.200 1578 122 B RGB/00148.bmp 11:24:02.233 1611 160 B RGB/00149.bmp 11:24:02.267 1632 198 B RGB/00150.bmp 11:24:02.300 1642 238 B RGB/00151.bmp 11:24:02.333 1645 267 B RGB/00152.bmp 11:24:02.367 1589 356 H RGB/00152.bmp 11:24:02.367 1663 312 B RGB/00153.bmp 11:24:02.400 1602 396 H RGB/00153.bmp 11:24:02.400 1667 345 B RGB/00154.bmp 11:24:02.433 1607 414 H RGB/00154.bmp 11:24:02.433 1658 369 B RGB/00155.bmp 11:24:02.467 1635 392 B RGB/00156.bmp 11:24:02.500 1612 410 B RGB/00157.bmp 11:24:02.533 1532 392 H



#### Issue discussed last time:



#### Issue discussed last time:

- Did rigorous checks to ensure algorithm is correct
- Confirmed that heading calculation was correct
- Verified end-to-end

#### Issue discussed last time:



**Further testing:** 

Did not face GPS logging issues but in camera synchronization

# **Processing Pipeline**



#### Processing pipeline

## Code migration to Python

• Thermal detection algorithm is finished



Thanks!