## Team NightWalkers (B)

## **SVD Test**

- 1. Demo Name: Human Detection Test
  - a. Relevant Requirements: RPM-4
  - b. Location: MRSD Lab, Level B
  - c. Equipment:
    - i. Unitree robot hardware
    - ii. Joystick controller
    - iii. Laptop
  - d. Personnel: Saha
  - e. Procedure:
    - i. Turn on the robot and make sure all components function properly
    - Use the joystick controller to make sure the robot is controllable and able to move forward/backward/sideward
    - iii. Walk the robot past three static humans with varying levels of occlusion
  - f. Verification Criteria:
    - i. All human shapes are recognized
- 2. Demo Name: Footstep Planning Test
  - a. Relevant Requirements: RPM-3
  - b. Location: MRSD Lab, Level B
  - c. Equipment:
    - i. Unitree robot hardware
    - ii. Joystick controller
    - iii. Laptop
  - d. Personnel: Saha
  - e. Procedure:
    - i. Turn on the robot and make sure all components function properly
    - ii. Use the joystick controller to make sure the robot is controllable and able to move forward/backward/sideward
    - iii. Give joystick commands for the direction in that the robot must move
  - f. Verification Criteria:
    - i. The robot can recognize the obstacle and climb it effectively