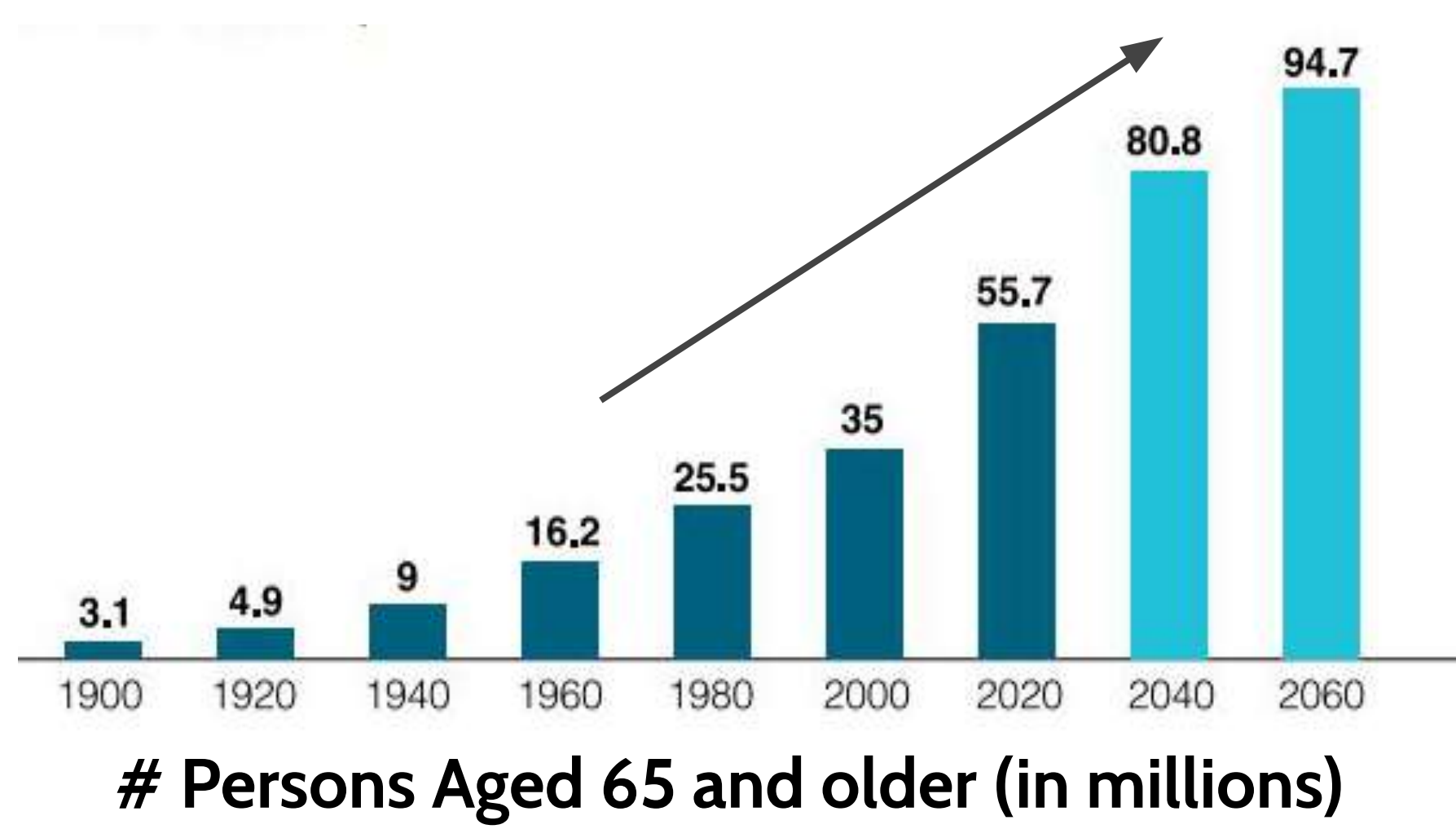




## Problem Statement

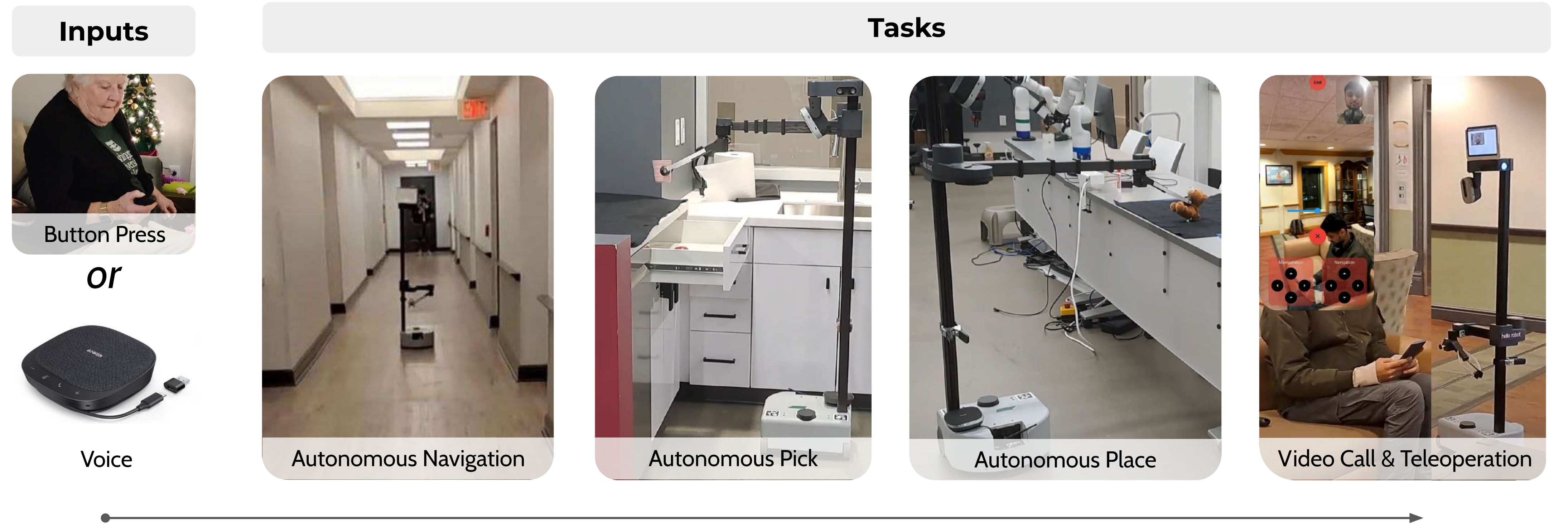
- Huge labour shortage in Assisted Living
- Elderly are fastest growing population



- Assist elders with low-risk tasks
- Improve independence
- Empower caretakers
- Bring family members closer

- Build an automated solution that augments elderly caregiving.

## Use Case



Once triggered, mix and match tasks!

## System Design

### Button Task Input

Handheld remote Task input modality

Room Ground Station Raspberry Pi

### Navigation

3D Navigation

### VLMaps - Semantics for Natural Language Navigation

Query: "sofa"

### Emotion Engine

Complex transition functions modelled on the human eye

### Manipulation

YOLOv8 Coarse perception for scene understanding

DETIc Open Vocabulary Instance Segmentation for Grasping

Grasp Generation GraspNet (cloud), 3DBoxGen (on-device), Success Recognition - (visual and proprioceptive)

TSDF Reconstruction, Reachability Analysis

Discretized pre-grasp planning

### System Design

Firestore

audio

GPT-4: long horizon task planning

```

2 # Find above it and place them all inside the drawer.
3 # Come back to me (user) and then crack a joke
4
5 def execute_plan():
6     if not go_to('drawer'):
7         return False, "I cannot go to the drawer"
8
9     detections = get_detections()
10    open_drawer()
11    for detection in detections:
12        object_picked = pick(detection)
13        if object_picked:
14            place('drawer')
15    close_drawer()
16
17    if not go_to('user'):
18        return False, "I cannot go to you"
19
20    speak("Why don't scientists trust atoms? Because they make up everything!")
21    return True, "Success"
22

```

Robust pick & place Deployment in ALF

## Results & Conclusion

### CMU Team Explores Future of Caregiving With Assistive Robot

Carnegie Mellon University students recently gave residents of a senior living community a taste of robot-delivered ice cream while demonstrating the potential future of caregiving.

A team of graduate students in the Robotics Institute took a robot named Alfred to Vitalia North Olmsted, a senior living community outside Cleveland. Designed to assist the elderly with daily activities like fetching and delivering objects, Alfred consists of a rolling base not much larger than a robotic vacuum and a long pole-like body with an arm and gripper.

After the residents ate lunch, it was showtime for Alfred. For dessert, the CMU team set up cups of ice cream. Residents approached Alfred, requested a flavor, and watched as the robot navigated to the appropriate cup and handed them the ice cream.

"The residents were overwhelmingly excited about the robot," said Zackory Erickson, an assistant professor in the Robotics Institute and co-advisor of the students working on Alfred.

After delivering dessert, Alfred mingled with the crowd, showing off its social skills by making basic conversation and responding to questions about the robot.

